Computer Image Processing Lecture 9

Morphological operations

Mathematical morphology

Mathematical morphology is a theory and technique for the analysis and processing of geometrical structures.

It was originally developed for binary images, and was later extended to grayscale functions and images.

The research began in the 1960s at the Center de Morphologie Mathématique at the Paris School of Mines (Fontainbleau) - G. Matheron, J. Serra.

Binary images could be treated as sets – object in the picture is a set of all elements (pixels) which value is equal to 1.

Translation by a vector $t = (t_x, t_y)$

$$A_t = \{a + t : a \in A\}$$

The set A translated by a vector t – coordinates of each image pixel (x,y) are transformed to (x + t_x , y + t_y).

Translation by a vector $t = (t_x, t_y)$

Set A

Set *A* after translation by the vector *t*

Underlined element denotes the center of coordinate system.

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Symmetrical mirroring of the set relative to the origin of the coordinate system

						$A^* = \{-a : a \in A\}$					
	$\begin{bmatrix} 0 \end{bmatrix}$	0	0	0	0		$\begin{bmatrix} 0 \end{bmatrix}$	0	0	0	0
	0	0	0	0	0		0	0	1	1	0
A =	0	1	1	0	0	A*=	0	0	1	1	0
	0	1	1	0	0		0	0	0	0	0
	0	0	0	0	0		0	0	0	0	0

Set A

Set *A* after mirroring

Underlined element denotes the origin of coordinate system.

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Minkowski addition

$$A \oplus B = \{p : p = a + b, a \in A, b \in B\}$$

a and *b* are pairs (vectors) belonging to different sets

Example:

$$A = \{(0,0), (0,1), (-1,0)\}$$
$$B = \{(0,0), (0,1), (1,1)\}$$
$$A \oplus B = \{(0,0), (0,1), (1,1), (0,2), (1,2), (-1,0), (-1,1)\}$$

Minkowski addition

$$A = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \qquad B = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \qquad A \oplus B = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Minkowski subtraction

$$A \ominus B = (A' \oplus B^*)'$$

where:

 $A' = \{a' : a' \notin A\}$ - complement of set A $B^* = \{-b : b \in B\}$ – mirroring of set B relative to the origin of the coordinate system

$$A \ominus B = \{a : a + b \in A, \text{ for each } b \in B\}$$

Minkowski subtraction

$$A = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & 1 \end{bmatrix} \qquad A B = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Basic operations:

- dilation,
- erosion,
- opening,
- closing.

Other operations:

- thickening/thinning,
- morphological skeleton,
- pruning transform,
- hit-or-miss

The basic idea in binary morphology is to probe an image with a simple, pre-defined shape, drawing conclusions on how this shape fits or misses the shapes in the image. This simple "probe" is called the **structuring element** and is itself a binary image.



The difference between morphological operations and other operations on the image:

- contextless operations do not take into consideration neighbouring pixels,
- context operations (filters) calculations are performed on each pixel of the image with taking into account neighbouring pixels,
- **morphological operations** performed only on pixels, whose surroundings are equal to the pattern.

Dilation - is an operation of extending the base set, which combines two sets with the use of a vector addition. The dilation of sets A and B leads to the creation of a set of all *p* points representing vector sums of any pairs of elements of sets A and B.



 $A \bigoplus B = \{p : p = a + b, a \in A, b \in B\}$

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Source image

Image after dilation

Added pixels

Dilation is used to fill narrow gaps and small holes in the image, connect parts located close to each other, generalize the image and smooth the edges.

Easiest way to describe it is to imagine the same text is written with a thicker pen.

If a structuring element 3 *x* 3 is used for dilation, the object is enlarged by a 4-contour.

Source image

Image after five-times dilation with the use of structuring element 3x3.

Source image

Image after five-times dilation with the use of structuring element 3x3.

Erosion - means a set of all points *a* such that *a* shifted by *b* is contained in A

 $A \ominus B = \{a : a + b \in A, \text{ for each } b \in B\}$

The result is determined only by the points *a*, for which $a + b \in A$

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Source image

Image after erosion

Removed pixels

Erosion is used to simplify the structure of the object, remove small details, smooth the edge, divide the object compound into several simpler components.

Erosion is an additive transformation, i.e. the effect of complex erosion is the same as the effect of successive straight transformations.

The use of a longitudinal shaped structuring element allows to distinguish longitudinal shapes in the image in a direction similar to the direction of the structuring element.

Source image

Image after five-times erosion with the use of structuring element 3x3.

Source image

Image after five-times erosion with the use of structuring element 3x3.

Comparison of the effect of morphological operations

Source image

Image after dilation

Image after erosion

Comparison of the effect of morphological operations

Source image

Image after dilation

Image after erosion

Opening and closing

Erosion and dilation are not fully reversible operations. Used sequentially, they do not give as a result the source image, as it is usually significantly simplified.

Opening = erosion + dilation $A \circ B = (A \ominus B) \oplus B$

Closing = dilation + erosion $A \cdot B = (A \oplus B) \ominus B$

The point of **opening** is to move the circle (structuring element) on the inside of the edge of the figure and rejecting all those points that can not be reached by the wheel.

That transformation is used to remove small objects, depressions and bulges, to disconnect objects with constrictions.

Opening

Source image

Image after opening

Source image

Image after opening

Source image

Image after opening

The point of **closing** is to move the circle (structuring element) on the outside of the edge of the figure and adding to it all those points that can not be reached by the wheel.

An operation that can be used to fill gaps and small holes inside the object.

Opening and closing do not change the shape or area of objects with large dimensions and smooth contour.

Closing

Source image

Source image

Source image

Comparison between opening and closing

Image after opening

Image after opening

Image after closing

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Source image

Image after opening and closing

Hit-or-miss transform is an operation that detects a given configuration (or pattern) in a binary image, using the morphological erosion operator and a pair of disjoint structuring elements. The result of the hit-or-miss transform is the set of positions where the first structuring element fits in the foreground of the input image, and the second structuring element misses it completely.

Hit-or-miss

Element $B = (B_1, B_2)$ on the assumption $B_1 \cap B_2 = \emptyset$ can be presented in the form of one pattern in the way that by the value of 1 the pixels of the element are supposed to hit the pixels of the object with the value 1 and by 0 those that have to hit the surroundings, i.e. the image pixels with the value 0.

$$HTM(A,B) = \{p : B_1 \subset A \mid B_2 \subset A'\}$$

Hit-or-miss

In Matlab following elements of the pattern denotes:

- 1 points to hit the analyzed object
- -1 points to miss it
- 0 points without matter

Hit-or-miss

Examples of structuring elements that can be used to detect characteristic elements of an image:

isolated points

endpoints

nodes