Chapter 3: Signals Analog and Digital Signals

To be transmitted, data must be transformed to electromagnetic signals.

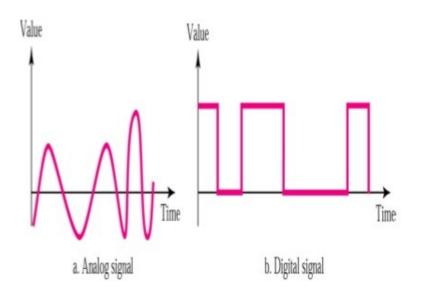
Analog and Digital

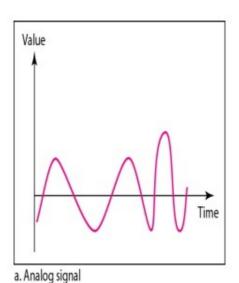
- **M**Analog and Digital Data
- **M**Analog and Digital Signals
- Periodic and Aperiodic Signal

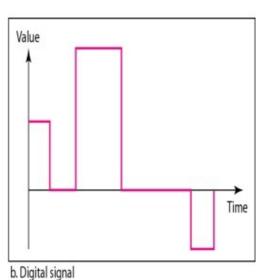
Data

//Data can be

- Analog
 - infinite number of values in a range
- Digital
 - *A*limited number of defined values

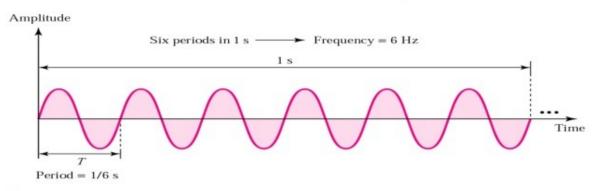




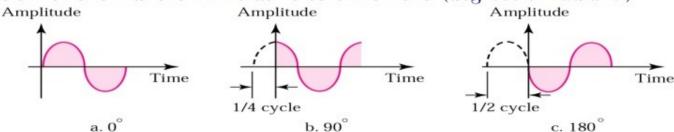


Analog Signals

// Sine wave: most fundamental form of a periodic analog signal



- Amplitude
 - ∧ Absolute value of a signal's highest intensity, Normally in volts
- Frequency
 - ∧ number of periods in one second, inverse of period
 - ∧ Change in a short span of time means high frequency
- Phase
 - ∧ Position of the waveform relative to time zero (degrees or radians)



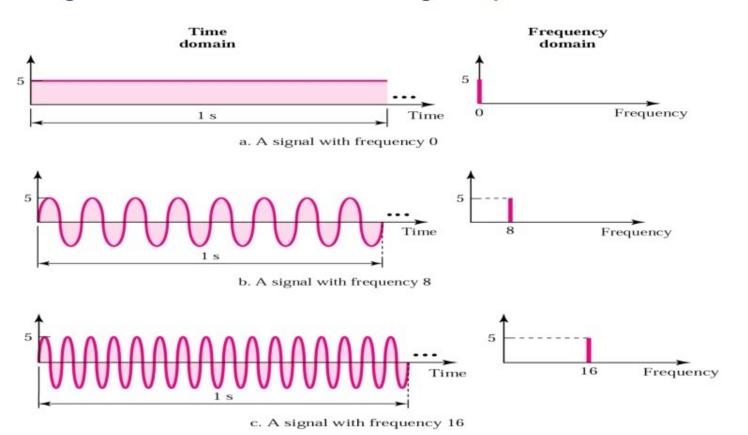
Time and Frequency Domains

//Time-domain plot

displays changes in signal amplitude with respect to time

// Frequency-domain plot

compares time domain and frequency domain



Digital Signals

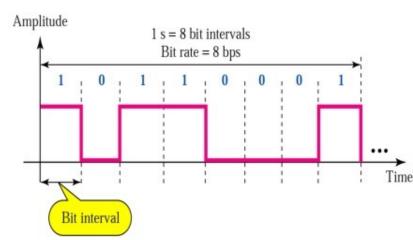
- // Use binary (0s and 1s) to encode information
- Less affected by interference (noise)
- // Fewer errors
- // Describe digital signals by
 - Bit interval
 - Bit rate
 - ∧ number of bit intervals per sec (bps)

Analog bandwidth

range of frequencies a medium can pass (hertz)

// Digital bandwidth

maximum bit rate that a medium can pass (bps)



Data Rate Limits

- // How to determine the maximum bit rate (bps) over a channel?
 - Data rate depends on 3 factors
 - ▲Bandwidth available
 - ∠Levels of signals we can use
 - ∠ Quality of the channel (level of noise)
- Two theoretical formulas were developed to calculate the data rate
 - Nyquist for a noiseless channel
 - Shannon for noisy channel

Noiseless Channel Nyquist Bit Rate

Defines the theoretical maximum bit rate Bit Rate = 2 Bandwidth log₂ L

L is the number of signal levels used to represent data

Example

Consider a noiseless channel with a bandwidth of 3000 Hz transmitting a signal with two signal levels. The maximum bit rate can be calculated as

Bit Rate = $2 \gg 3000 \gg \log_2 2 = 6000$ bps

Noisy Channel Shannon Capacity

Determine the theoretical highest data rate for a noisy channel $C = B \log_2 (1 + SNR)$

Example

We can calculate the theoretical highest bit rate of a regular telephone line. A telephone line normally has a bandwidth of 3000 Hz (300 Hz to 3300 Hz). The signal-to-noise ratio is usually 3162.

then Channel capacity = $3000 \log_2 (1 + 3162)$ = $3000 \log_2 (3163)$ = 3000 11.62 = 34,860 bps

Transmission Impairment

- // Imperfections cause impairment, which means that a signal at the beginning and the end of the medium are not the same
- M Three types of impairments
 - 1) Attenuation
 - ∠Loss of energy, Amplifiers are used to strengthen
 - ⚠ To show that a signal has lost or gained strength, engineers use the concept of decibel (db)

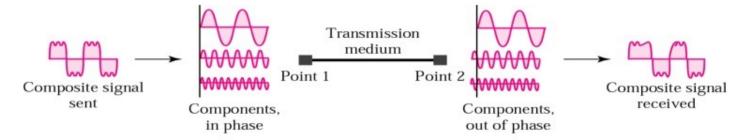
Example

A signal travels through a transmission medium and its power is reduced to half. This means that P2 = 1/2 P1. Calculate the attenuation (loss of power)?

```
attenuation = 10 \log 10 (P2/P1)
= 10 \log 10 (0.5P1/P1)
= 10 \log 10 (0.5)
= 10(-0.3) = -3 dB
```

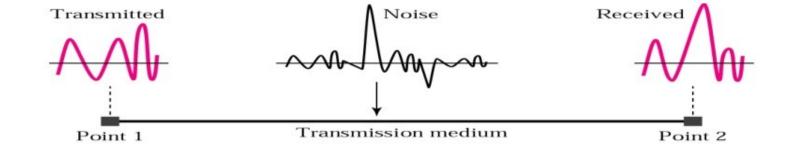
2) Distortion

- Signal changes form or shape
- Each component has its own propagation speed, therefore its own delay in arriving



3) Noise

- Thermal noise random motion of electrons, creating an extra signal
- Induced noise outside sources such as motors and appliances
- Crosstalk effect of one wire on another
- Impulse noise a spike for a short period from power lines, lightning



Digital Transmission

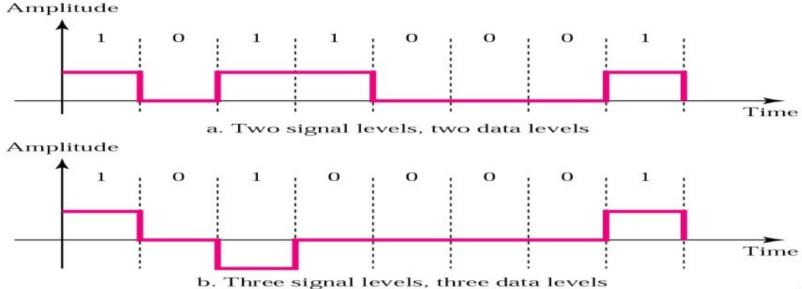
Ch4

- // Methods to transmit data digitally
 - 1) Line coding
 - Process of converting binary data to a digital signal
 - 2) Block coding

 - ⚠ Three steps
 - Division
 - Substitution
 - Line coding
 - 3) Sampling
 - is process of obtaining amplitudes of a signal at regular intervals
- Transmission modes
 - Parallel
 - Serial
 - Synchronous
 - Asynchronous

Signal Level versus Data Level

- // Signal level
 - number of values allowed in a particular signal
- // Data level
 - number of values used to represent data
- M Note: figure b should say three signal levels, two data levels



Pulse Rate versus Bit Rate

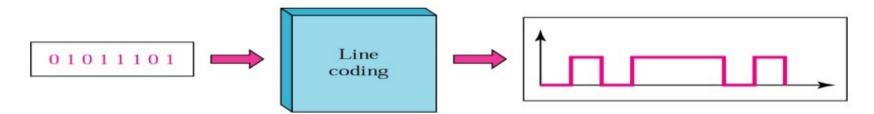
- // Pulse
 - minimum amount of time required to transmit a symbol
- // Pulse rate
 - defines number of pulses per second
- // Bit rate
 - defines number of bits per second
 - BitRate = PulseRate $x \log_2 L$
 - where L is the number of data levels

A signal has four data levels with a pulse duration of 1 ms. We calculate the pulse rate and bit rate as follows:

```
Pulse Rate = 1000 pulses/s
Bit Rate = PulseRate x log<sub>2</sub> L
= 1000 x log<sub>2</sub> 4 = 2000 bps
```

Line Coding

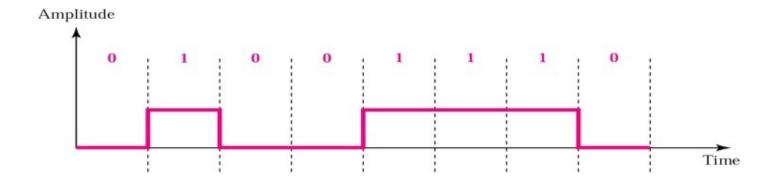
// Process of converting binary data to a digital signal



- // Line Coding schemes
 - Unipolar
 - Polar
 - Bipolar

Unipolar

- // Uses only one voltage level
- M Polarity is usually assigned to binary 1; a 0 is represented by zero voltage



- // Potential problems:
 - DC component
 - Lack of synchronization

Polar

// NRZ

Value of signal is always positive or negative

// NRZ-L

- Signal level depends on bit represented
 - ****positive** usually means 0
 - *∧***negative** usually means 1
- Problem: synchronization of long streams of 0s or 1s

// NRZ-I (NRZ-Invert)

- Inversion of voltage represents a 1 bit
- 0 bit represented by no change
- Allows for synchronization
- Long strings of 0s may still be a problem

Polar

// NRZ

Value of signal is always positive or negative

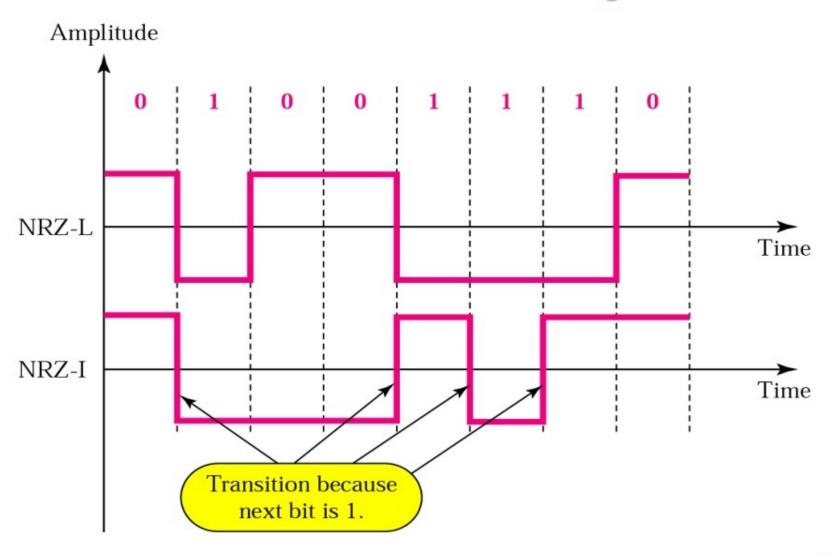
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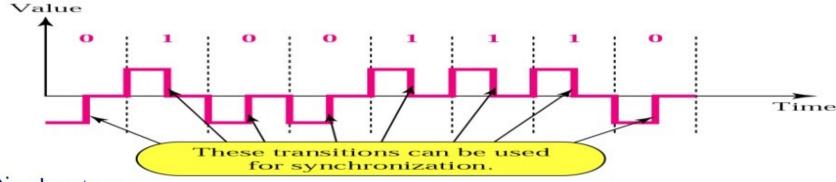
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- Allows for synchronization
- Long strings of 0s may still be a problem

NRZ-L and NRZ-I Encoding



Return to Zero (RZ)

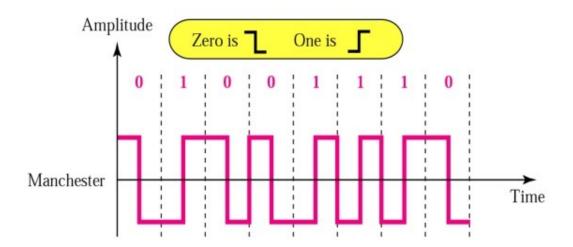
- // May include synchronization as part of the signal for both 1s and 0s
- // How?
 - Must include a signal change during each bit
 - Uses three values: positive, negative, and zero
 - 1 bit represented by pos-to-zero
 - 0 bit represented by neg-to-zero



- // Disadvantage
 - Requires two signal changes to encode each bit; more bandwidth necessary

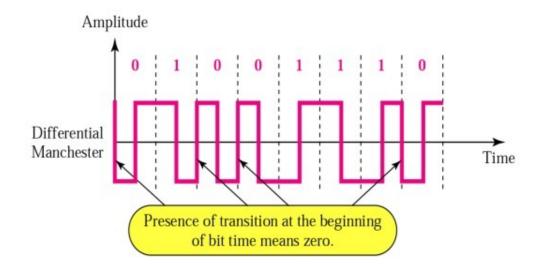
Manchester

- M Uses an inversion at the middle of each bit interval for both
 synchronization and bit representation
- // Negative-to-positive represents binary 1
- // Positive-to-negative represents binary 0
- // Achieves same level of synchronization with only 2 levels of amplitude



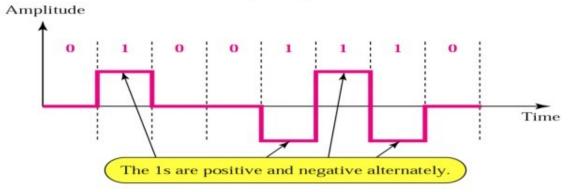
Differential Manchester

- // Inversion at middle of bit interval is used for synch
- Presence or absence of additional transition at beginning of interval identifies the bit
- / Transition □ 0; no transition □1
- // Requires two signal changes to represent binary 0; only one to represent 1



Bipolar Encoding

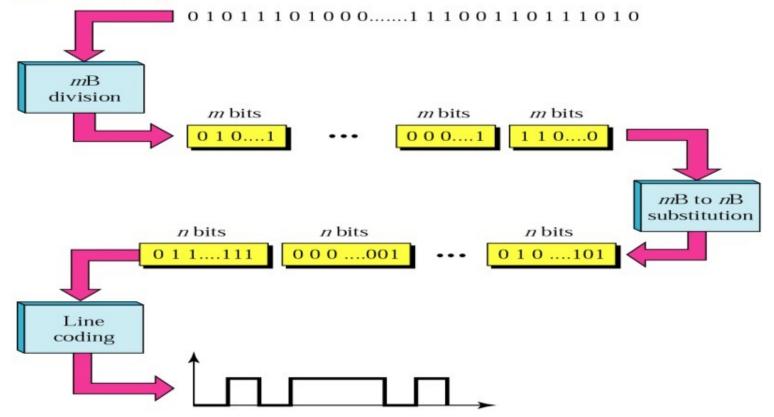
- // Uses 3 voltage levels: pos, neg, and zero
 - Zero level □ 0
 - 1s are represented with alternating positive and negative voltages, even when not consecutive
- // Two schemes
 - Alternate mark inversion (AMI)



Bipolar n-zero substitution (BnZS)

Block Coding

- // Coding method to ensure synchronization and detection of errors
- // Three steps
 - Division
 - Substitution
 - Line coding

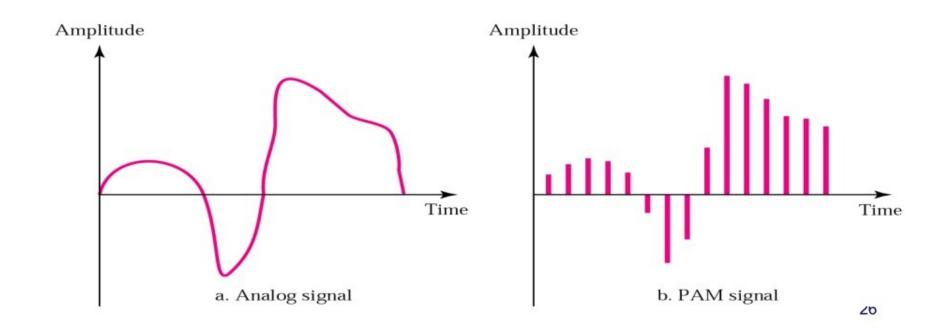


Sampling

- Analog data must often be converted to digital format (ex: long-distance services, audio)
- Sampling is process of obtaining amplitudes of a signal at regular intervals

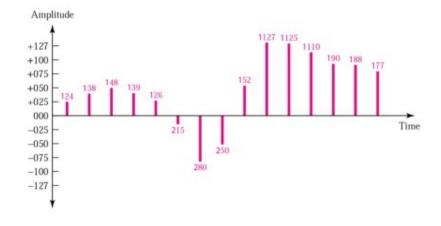
Pulse Amplitude Modulation

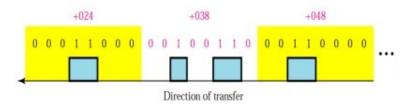
- Analog signal's amplitude is sampled at regular intervals; result is a series of pulses based on the sampled data
- Pulse Coded Modulation (PCM) is then used to make the signal digital



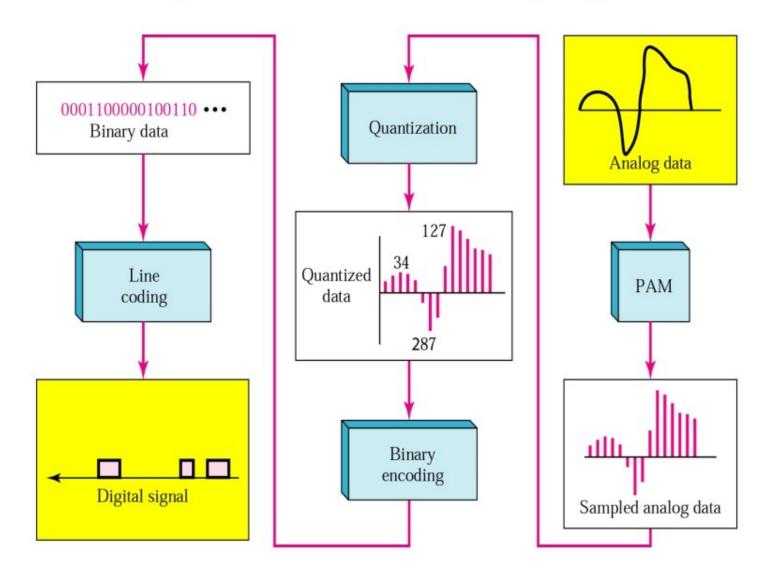
Pulse Coded Modulation

- First quantizes PAM pulses; an integral value in a specific range to sampled instances is assigned
- Æ Each value is then translated to its 7-bit binary equivalent
- Binary digits are transformed into a digital signal using line coding





Digitization of an Analog Signal



Sampling Rate: Nyquist Theorem

- Accuracy of digital reproduction of a signal depends on number of samples
- // Nyquist theorem
 - number of samples needed to adequately represent an analog signal is equal to twice the highest frequency of the original signal

Example

What sampling rate is needed for a signal with a bandwidth of 10,000 Hz (1000 to 11,000 Hz)? Each sample is 8 bits

Solution

The sampling rate must be twice the highest frequency in the signal Sampling rate = $2 \times (11,000)$

= 22,000 samples/sec

Bit rate = sampling rate x number of bits /sample

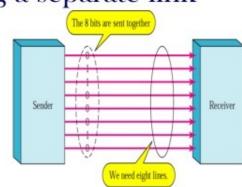
 $= 22000 \times 8$

= 172 Kbps

4.4 Transmission Mode

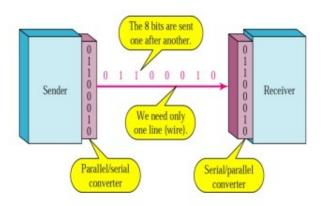
//Parallel

- Bits in a group are sent simultaneously, each using a separate link
- n wires are used to send n bits at one time
- Advantage: speed
- Disadvantage: cost; limited to short distances



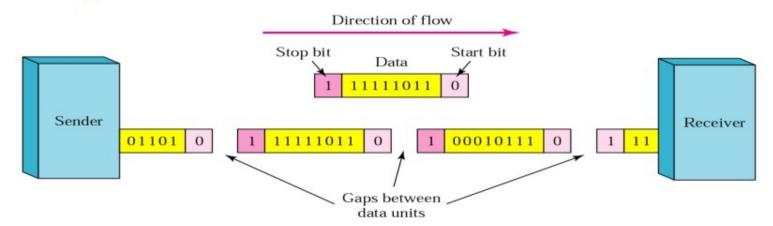
//Serial

- Transmission of data one bit at a time using only one single link
- Advantage: reduced cost
- **Disadvantage:** requires conversion devices
- Methods:
 - ∧ Asynchronous
 - *▲* Synchronous



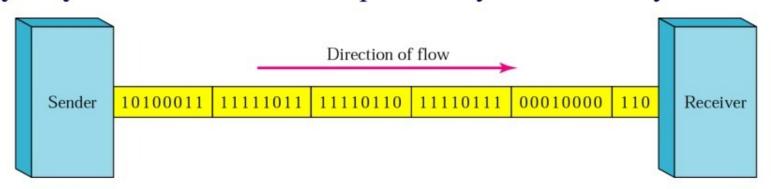
Asynchronous Transmission

- Slower, ideal for low-speed communication when gaps may occur during transmission (ex: keyboard)
- Transfer of data with start and stop bits and a variable time interval between data units
- Timing is unimportant
- Start bit alerts receiver that new group of data is arriving
- Stop bit alerts receiver that byte is finished
- Synchronization achieved through start/stop bits with each byte received □ Requires additional overhead (start/stop bits)
- Cheap and effective



Synchronous Transmission

- M Bit stream is combined into longer frames, possibly containing multiple bytes
- // Requires constant timing relationship
- Any gaps between bursts are filled in with a special sequence of 0s and 1s indicating idle
- // Advantage: speed, no gaps or extra bits
- // Byte synchronization accomplished by data link layer



Multiplexing

// Multiplexing

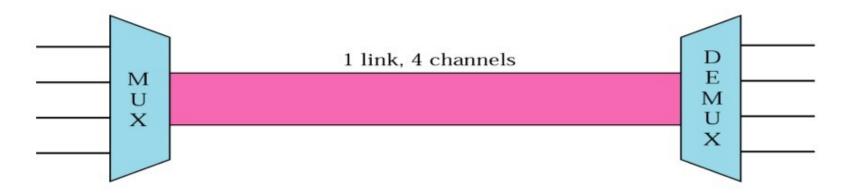
- A set of techniques that allows the simultaneous transmission of multiple signals across a single data link
- Can utilize higher capacity links without adding additional lines for each device better utilization of bandwidth

// Multiplexer (MUX)

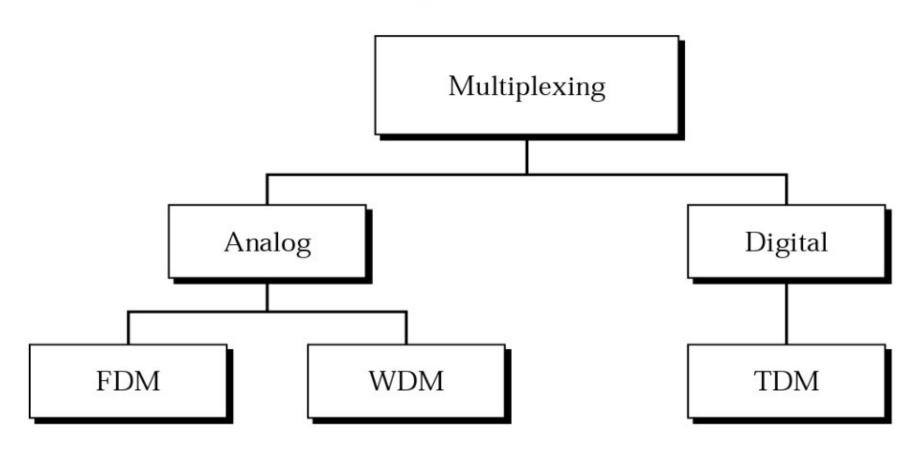
Combines multiple streams into a single stream (many to one).

// Demultiplexer (DEMUX)

 Separates the stream back into its component transmission (one to many) and directs them to their correct lines.

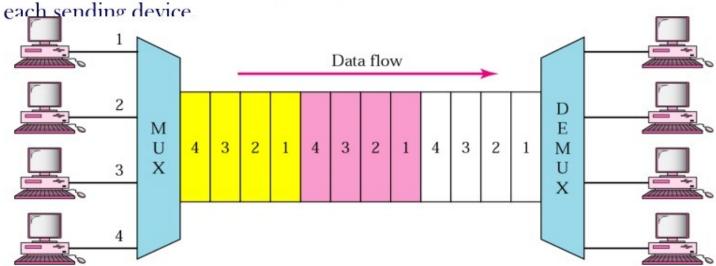


CATEGORIES OF MULTIPLEXING أصناف المجمعات



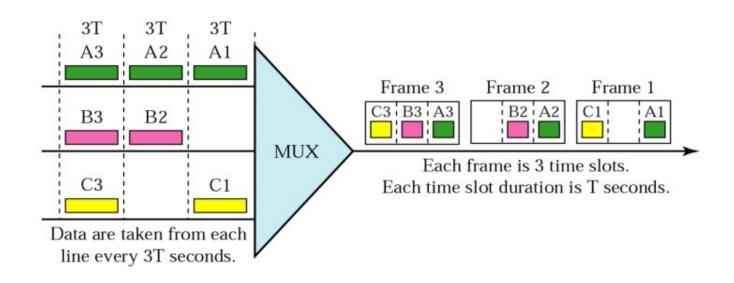
TIME DIVISION MULTIPLEXING

- M Digital process that allows several connections to share the high bandwidth of a link
- // Time Slots and Frames
 - Each host given a <u>slice of time</u> (time slot)
 - A frame consists of one complete cycle of time slots, with one slot dedicated to



TDM Frames

- // Mux-to-mux speed = aggregate terminal speeds
 - data rate of the link that carries data from *n* connections must be n times the data rate of a connection to guarantee the flow of data
 - i.e., the duration of a frame in a connection is n times the duration of a time slot in a frame

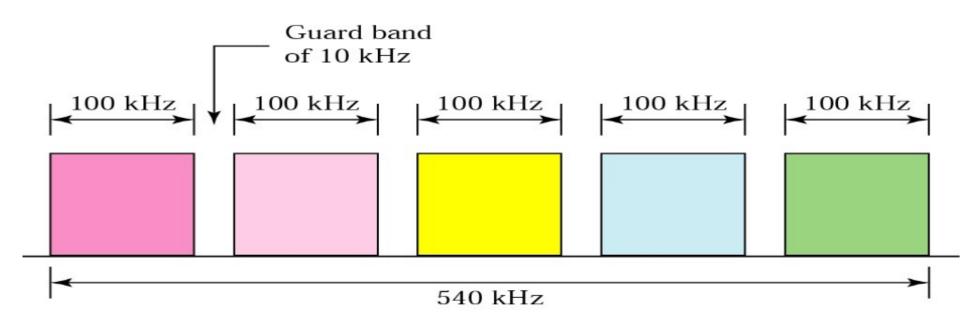


Example

5 channels, each with a 100-KHz B.W, are to be multiplexed together. What is the minimum B.W of the link if there is a need for a guard band of 10 KHz between the channels to prevent interference?

Solution

- // For 5 channels, we need at least 4 guard bands.
- // Uthe required B.W is at least $5 \times 100 + 4 \times 10 = 540 \text{ KHz}$



INTERLEAVING

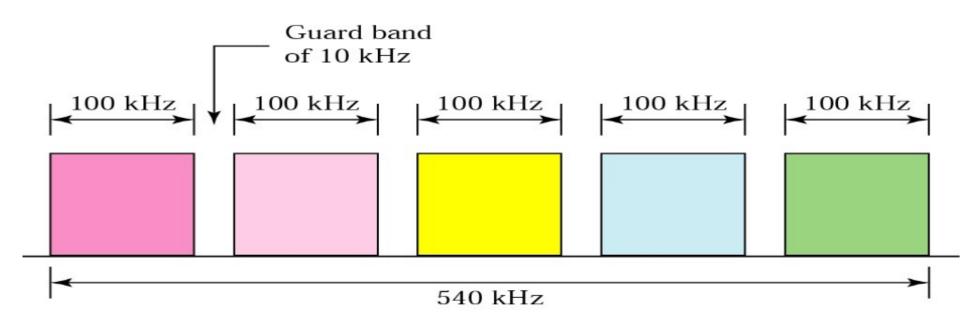
- // Process of taking a specific amount of data from each device in a regular order
- // May be done by bit, byte, or any other data unit
 - Character (byte) Interleaving
 - Multiplexing perform one/more character(s) or byte(s) at a time
 - Bit Interleaving
 - Multiplexing perform on one bit at a time

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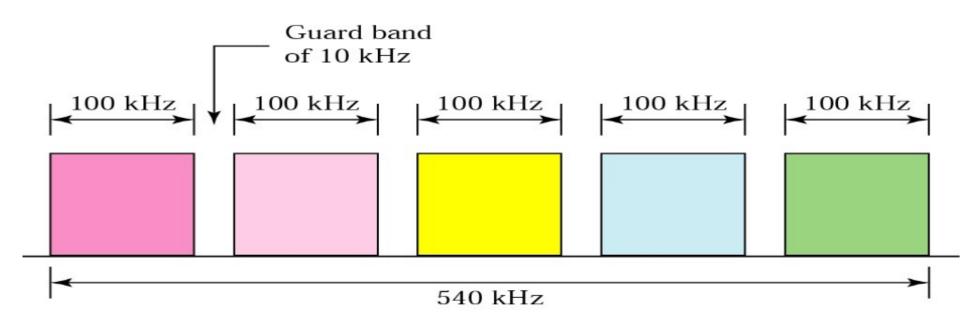


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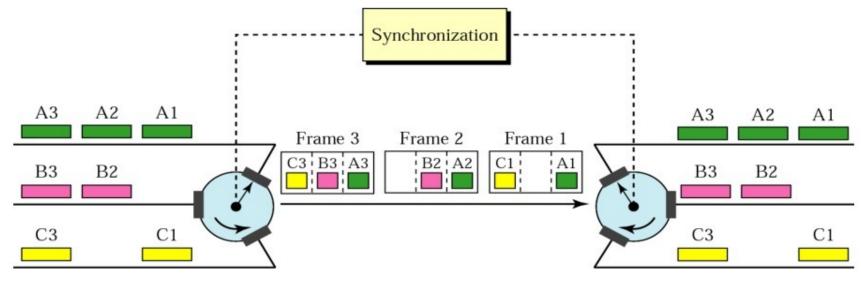
Solution

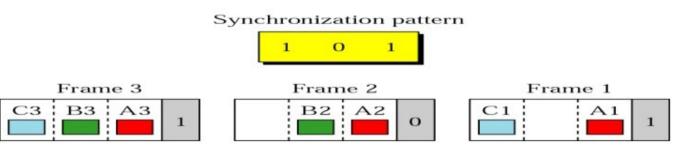
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SYNCHRONIZING

- Framing bit (s) is (are) added to each frame for synchronization between the MUX and DEMUX
 - synchronization bits allows the DEMUX to synchronize with the incoming stream so it can separate time slots accurately
- // If 1 framing bit per frame, framing bits are alternating between 0 and 1



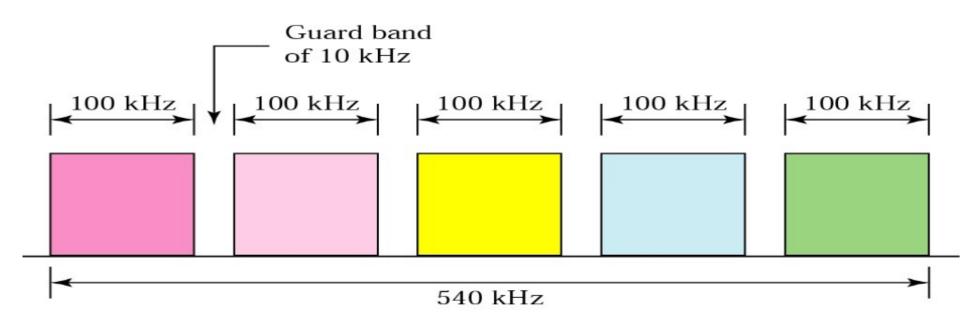


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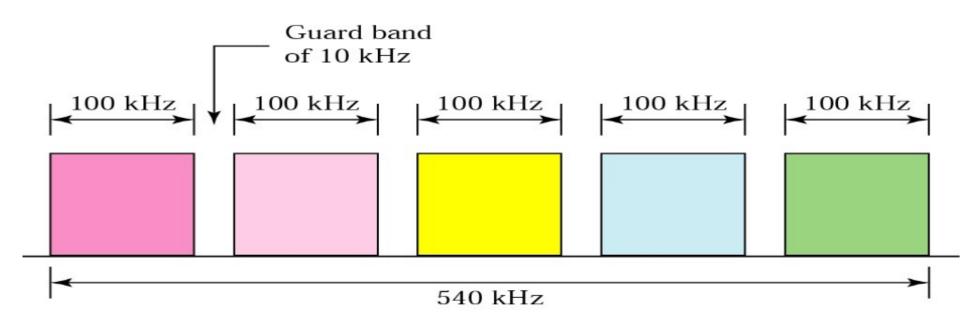


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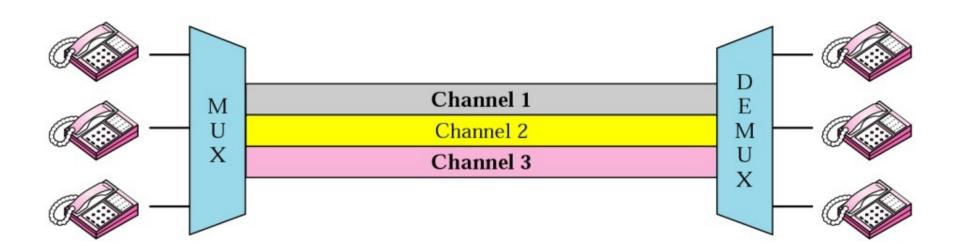


STDM

- // Mux-to-Mux speed < aggregate terminal/host speeds
- // Time slots allocated based on traffic patterns
 - uses statistics to determine allocation among users
 - must send port address with data (takes additional time slots)
- // May Potential loss of data during peak periods
 - may use data buffering and/or flow control to reduce loss
- // Not always transparent to user terminals and host/FEP
 - delays and data loss possible
- // So why use a stat mux?
 - more economical need fewer muxes, cheaper lines
 - more efficient allows more terminals to share same line
 - OK to use in many situations (e.g., terminal users

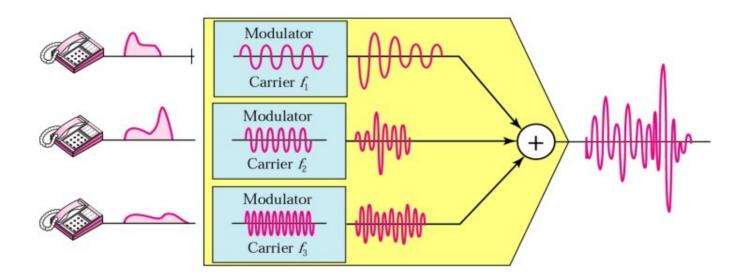
FREQUENCY DIVISION MULTIPLEXING

- // Assigns different analog frequencies to each connected device
- // Like Pure TDM,
 - mux-to-mux speed = aggregate terminal speeds
 - No loss of data so transparent to users and host/FEP
- // Channels must be separated by strips of unused B.W guard B.W



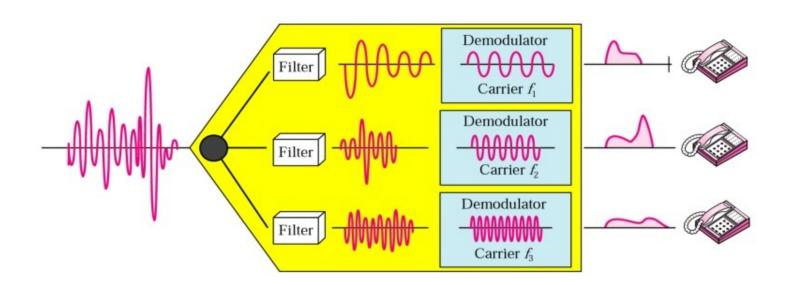
FDM PORCESS

- // Signals of each channel are modulated onto different carrier signal
- // The resulting modulated signals are then combined into a single composite signal that is sent out over a media link
- // The link should have enough bandwidth to accommodate it



FDM DEMULTIPLEXING

- Demultiplexer uses a series of filters to decompose the multiplexed signal into its constituent component signals
- // The individual signals are then passed to a demodulator that separates them from their carriers and passes them to the waiting receivers

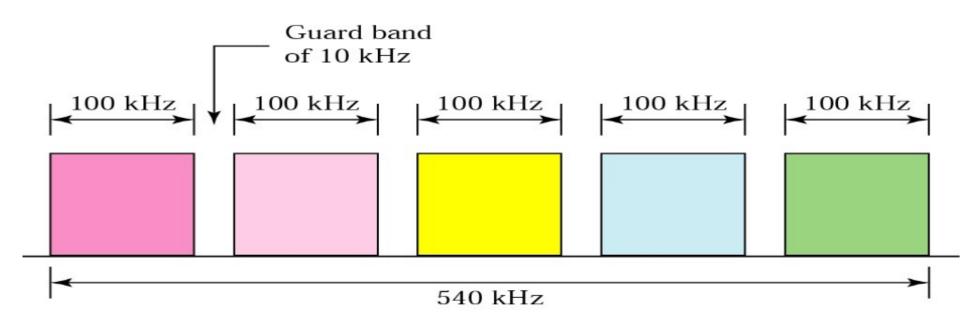


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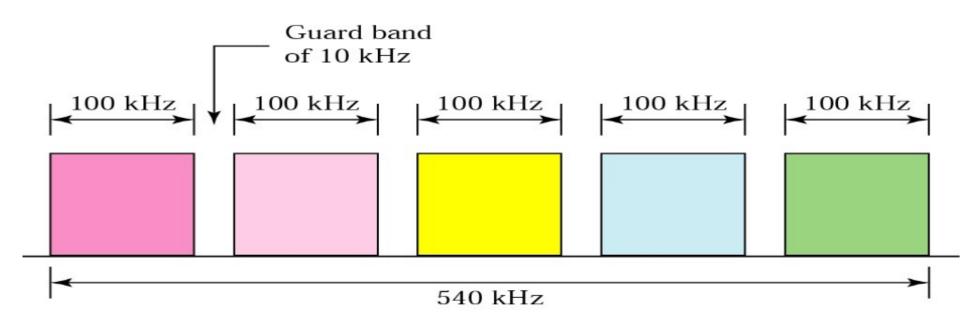


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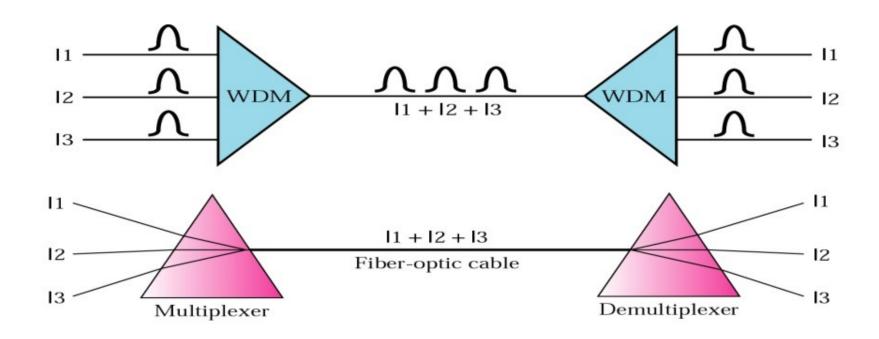
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Wave Division Multiplexing

- // An analog multiplexing technique to combine optical signals
- Multiple beams of light at different frequency
- // Carried by optical fibber
- A form of FDM
- ## Each color of light (wavelength) carries separate data channel
- // Commercial systems of 160 channels of 10 Gbps now available

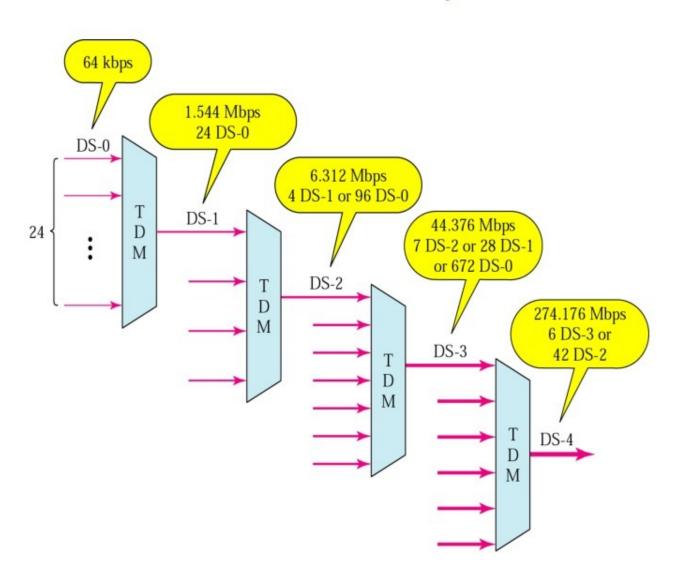


Digital Signal Service

- // Hierarchy of digital signals
 - DS-0 single channel of 64 Kbps
 - DS-1 single service or 24 DS-0 channels multiplexed 1.544Mbps
 - DS-2 single service or 4 DS-1 channels = 96 DS-0 channels = 6.312 Mbps
 - DS-3 single service, 7 DS-2 channels = 28 DS-1 channels = 672 DS-0 channels = 44.376 Mbps
 - DS-4 6 DS-3 channels

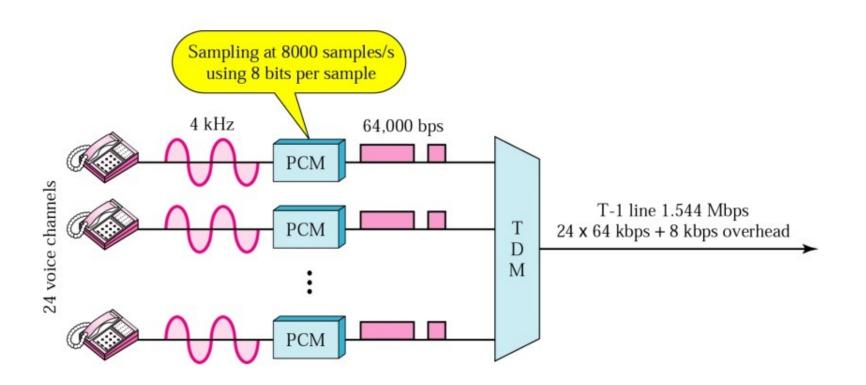
- = 42 DS-2 channel
- = 168 DS-1 channels
- = 4032 **DS-**0
- = 274.176 Mbps

DS Hierarchy

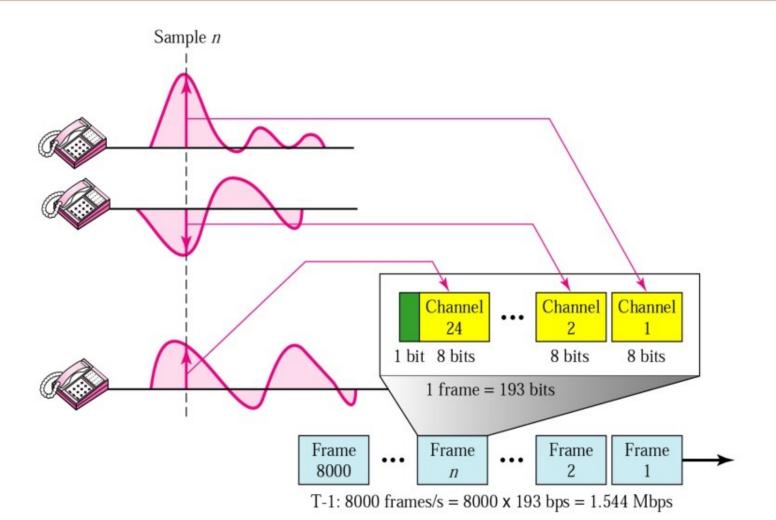


T Lines

- // Digital lines designed for digital data, voice, or audio
- May be used for regular analog (telephone lines) if sampled then multiplexed using TDM



T-1 frame structure



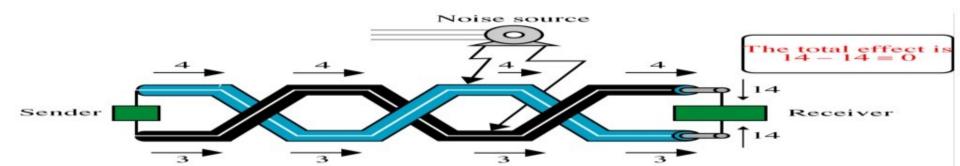
Chapter 7 Communications Media

- Medium

- the physical matter that carries the transmission.
- Two basic categories of media
 - Guided media
 - Transmission flows along a physical guide
 - Unguided media
 - there is no wave guide and the transmission just flows through the air (or space)

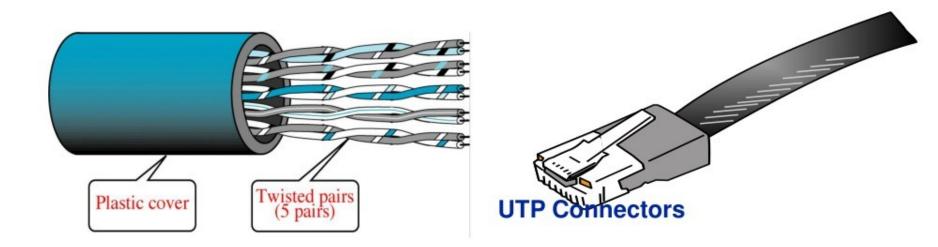
Twisted pair

- Use copper conductors that accept and transport signal in electrical forms
- Twisted pair can carry frequency range from 100Hz to 5MHz
- A twisted pair consists of two conductors (copper) each with coloured plastic insulation
- Twisted pair cable comes in two forms
 - Unshielded (UTP)
 - Shielded (STP)
- Problems with two parallel flat wires
 - Electromagnetic interference from devices such as motor can create noise affecting them
 - Uneven load may occur that could cause damage result from the wire closest to the source get more interference thus higher voltage level
- The 2 wires twisted around each other at regular intervals
 - Each wire is closer to the noise source for 1/2 the time and farther away for the other ½
 - The cumulative effect of the interference is equal on both wires
 - Twisting does not always eliminate the impact of noise but minimise it



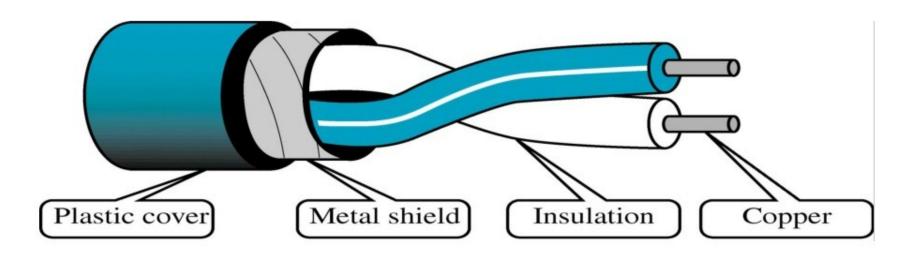
Unshielded (UTP)

- Most common type of telecommunication medium in use today
- Although is common in telephone systems, its frequency is capable of transmitting both data and voice



Shielded (STP)

- // Has a metal foil covering that encases each pair of insulated conductors
- // The metal casing which is connected to the ground prevents the penetration of electromagnetic noise
- // It can also eliminate crosstalk
 - Crosstalk occurs when one line picks up some of the signal travelling down another line



Advantages of UTP and UTP connectors

//Advantages:

- Cheap
- Flexible and easy to install
- // Higher grades of UTP are used in many LANs technologies (Ethernet and Token Ring)

Cable Categories

M The EIA (Electronic Industries Association) has developed the following categories with 1 as the lowest quality and 5 as the highest cable quality

Category 1

 used in telephone system; is fine for voice but not adequate for all but low-speed data communication

Category 2

suitable for voice and data transmission up to 4Mbps

Category 3

 required to have 3 twists per foot can be used for data transmission up to 10Mbps; most standard cable for telephone now

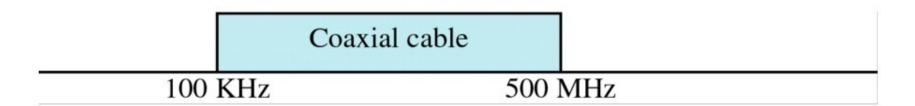
Category 4

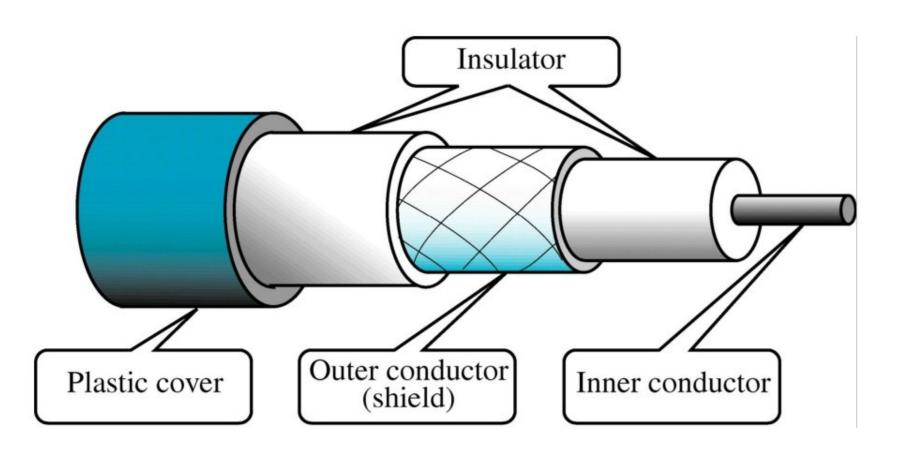
possible transmission rate to 16Mbps

Category 5

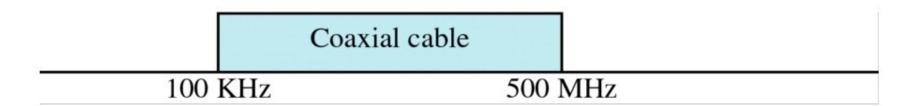
□ used for data transmission up to 100Mbps

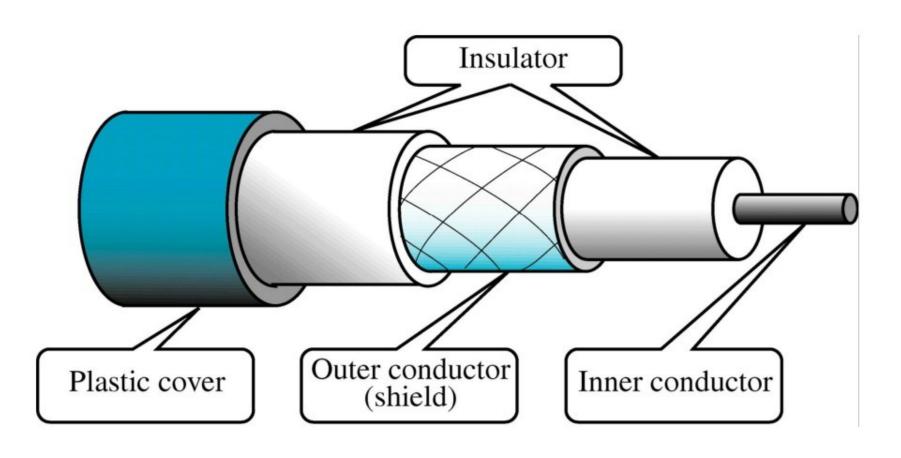
Coaxial Cable





Coaxial Cable





Coaxial Cable Connectors



Barrel connectors:

- Bayonet network connector (BNC) is the most popular, which pushes on and locks into place with a half turn
- Other types includes screw on, push on without locking
- Are familiar from cable TV and VCR hookups

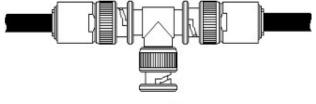






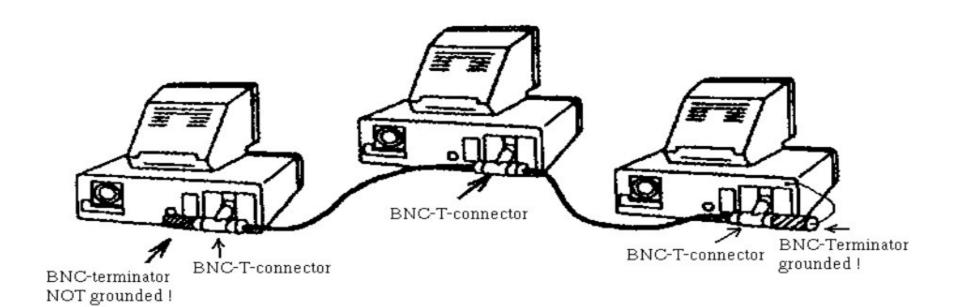
T-connector and Terminators

// T-connectors used in Ethernet that allows a secondary cable or cables to branch off from a main line



Terminators are needed where one main cable acts as a backbone with branches to several devices but does not terminate itself; absorbs the wave at the end and eliminates echo-back





Optical Fiber

- Made of glass or plastic and transmits signals in the form of light.
- Signal propagates along the inner core by reflection
- Advantages
 - Noise resistance: noise is not a factor as it uses light instead of electricity
 - Less signal attenuation: transmission distance is greater than other guide media
 - Higher bandwidth: currently the limit is govern by the signal generation and reception technology available

Disadvantages

- **Cost:** is expensive as manufacturing must be very precise and thus difficult to manufacture
- Installation/maintenance: any roughness or cracking in the core will diffuse the light and alter the signal, therefore care has to be taken when dealing with optical fiber
- **Fragility:** glass fiber is more easily broken than wire
- Signal propagation can be in 2 modes
 - Multi mode
 - multiple beams from a light source
 - Single Mode
 - one beam of light

Nature of light

- Light is a form of electromagnetic energy, travels at 300000 Km/sec in vacuum.
- // This speed decreases as the medium through which the light travels becomes denser.
- // It travels in straight lines through one substance.
- // The speed of light changes as rays travels through different substances causing these rays to change direction.
- When the light travels another substance, speed and direction changes (Refraction). Fiber optic technology takes advantages of this properties to control the propagation of light
- // When light cannot passes into the less dense medium, Optical fibres uses **reflection** to guide light through a channel

Multimode

Can further be break down into two forms

• Step-index:

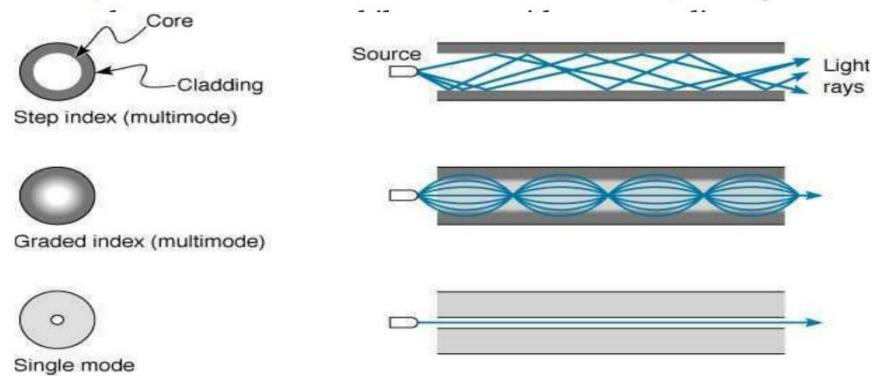
- AOther beams strike the interface of the core and cladding(غلاف) at different angles causing the beams to reach the destination at different times

• Graded-index:

Single Mode

• Uses step-index fiber and a highly focused source of light that limits beams to a small range of angles, all close to horizontal

• Expensive because it is difficult to manufacture, but **signal**



Fiber-optic

- // At the center is the glass core through which the light propagates
- // The core is surrounded by a glass cladding with a lower index of refraction than the core, to keep all the light in the core
- ## For transmission to take place, the sending device must equipped with a light source (LED or injection laser diode)
- // The receiving device uses photodiode to translate the received data

Unguided Media

Radio

- Wireless transmission of electrical waves
- ✓ Includes AM and FM radio bands

Infrared

- ✓ Used in remote control units (e.g., TV).

Microwave

- ∠ High frequency form of radio with extremely short wavelength (1 cm to 1 m).
- ⚠ Often used for long distance

Radio Transmission

#The properties of radio waves are frequency dependent

low frequencies

- ✓ power of signal falls off sharply over distance

high frequencies

- *★* bounce off obstacles
- *▲*absorbed by rain

at all frequencies

- *i*interference between users *i*
- ★therefore highly regulated

Radio Transmission

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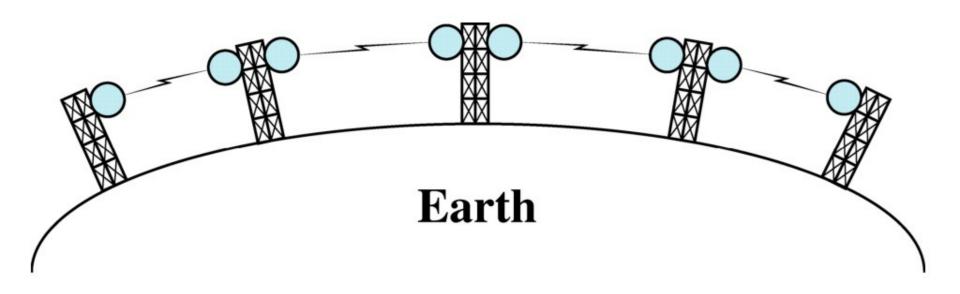
Infra-red

- //short-range communication (VCR remotes)
- //cheap
- //do not pass through solid objects
- //will not interfere with a similar system in adjacent rooms
- // better security against eavesdroppers

Microwave

- Requires line-of-sight transmission & reception equipment
 - ☐ Transmission is straight (from antenna-to-antenna)
- Signals propagate in one direction at a time.
- Two frequencies are required for 2-way communication
- For a telephone conversation we need one frequency for transmitting & another frequency for receiving.
- Each frequency requires its own transmitter & receiver.
- Now both are combined in a single piece called transceiver.
- To increase distance served, repeaters installed with each antenna.
- A signal received by one antenna is converted back into transmittable form and relayed to the next antenna.

Terrestrial Microwave



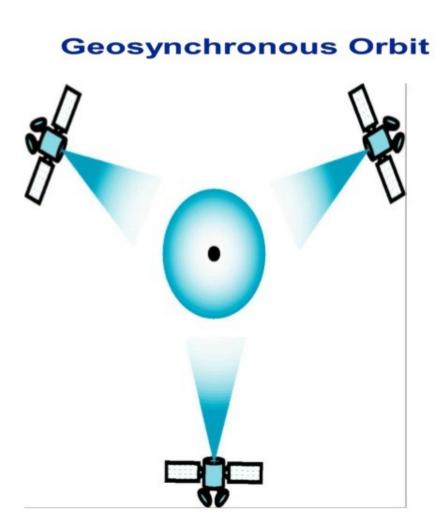
Satellite

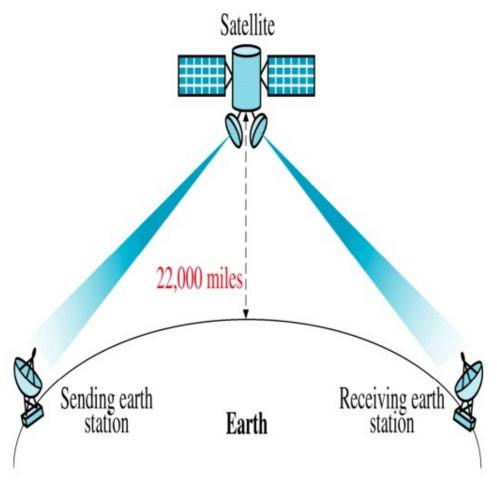
 Same as the terrestrial microwave, with a satellite acting as a super tall antenna and repeater.

Geosynchronous Satellites

- Line-of-sight propagation requires sending & receiving antennas be locked onto each other's location all times.
- To ensure constant communication, satellite must move at same speed as the earth so it seems to remain fixed above a certain spot.
- This satellite called Geosynchronous.
- Transmission from the earth to satellite is called **uplink**.
- Transmission from the satellite to earth is called **Downlink**

Satellite Communication

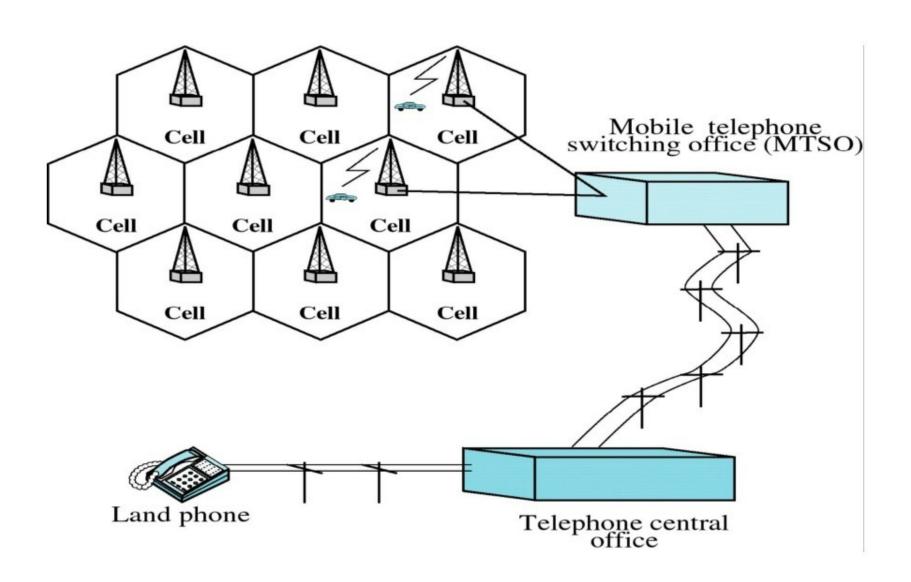




Cellular Telephony

- Provides communications connections between 2 moving devices or between one mobile unit & one land unit.
 - Service area is divided into small regions called cells.
 - Each cell contains an antenna & is controlled by small office called cell office
 - Each cell office is controlled by switching office called (MTSO) mobile telephone switching office.
 - Typical radius of a cell is 1-12 miles.
 - The transmission power of each cell is kept low to prevent its signal from interfering with those of other cells.

Cellular System



HANDOFF

- During a call, the mobile phone may move from one cell to another, then the signal becomes weak.
- To solve the problem the MTSO monitors the level of the signal every few seconds.
- If the strength of the signal diminishes, the MTSO seeks a new cell that can accommodate the communication better, then change the channel carrying the call.